

RELAY DRIVERS, LAMP DRIVERS,
MOTOR DRIVERS APPLICATION.

FEATURES

- Adoption of MBIT Processes.
- Large Current Capacitance.
- Low Collector-to-Emitter Saturation Voltage.
- High-Speed Switching.
- Ultrasmall Package Facilitates Miniaturization in end Products.
- High Allowable Power Dissipation.
- Complementary to KTC3551T.
- Suffix U : Qualified to AEC-Q101.
ex) KTA1551T-RTK/HU

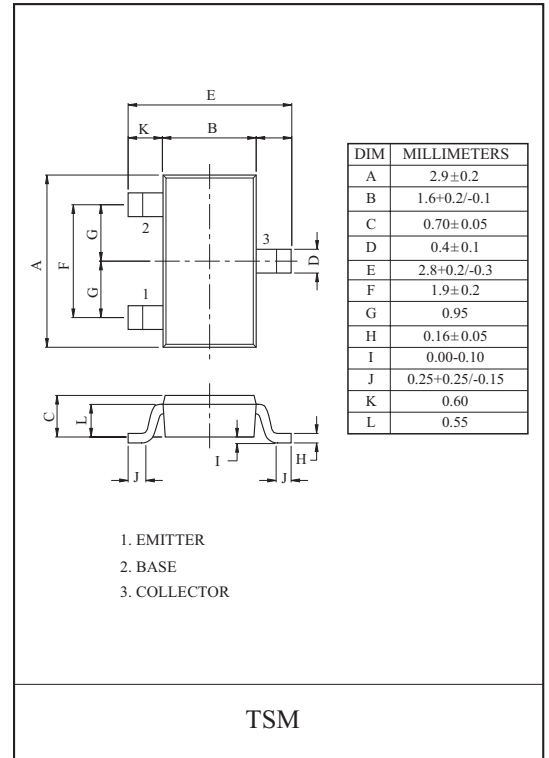
MAXIMUM RATING (Ta=25 °C)

CHARACTERISTIC		SYMBOL	RATING	UNIT
Collector-Base Voltage		V_{CBO}	-50	V
Collector-Emitter Voltage		V_{CES}	-50	V
		V_{CEO}	-50	
Emitter-Base Voltage		V_{EBO}	-5	V
Collector Current	DC	I_C	-1.0	A
	Pulse	I_{CP}	-3	
Base Current		I_B	-200	mA
Collector Power Dissipation		P_C^*	0.9	W
Junction Temperature		T_j	150	
Storage Temperature Range		T_{stg}	-55 150	

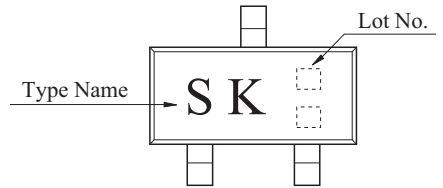
* Package mounted on a ceramic board (600mm² × 0.8mm)

ELECTRICAL CHARACTERISTICS (Ta=25 °C)

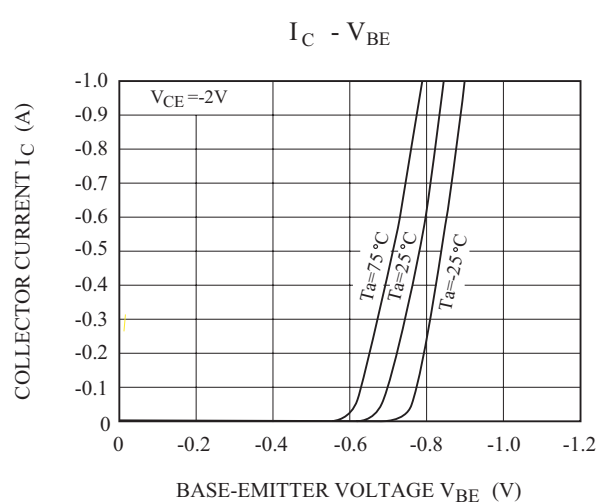
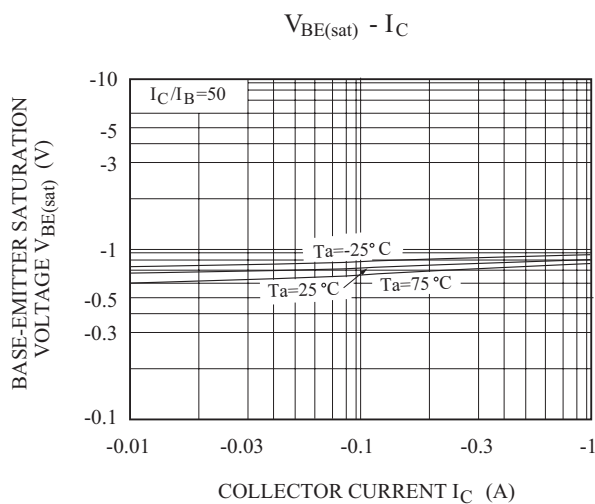
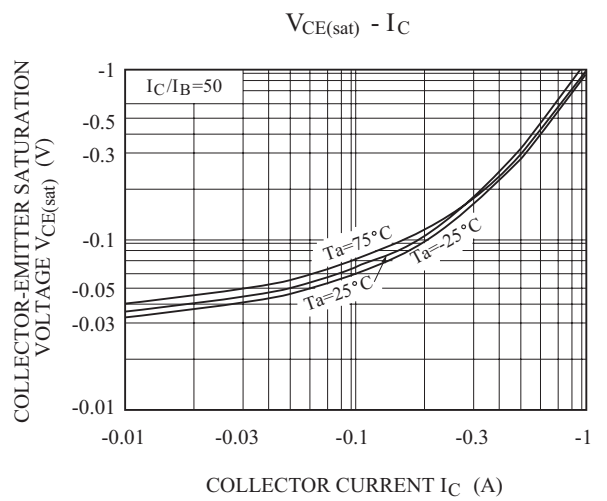
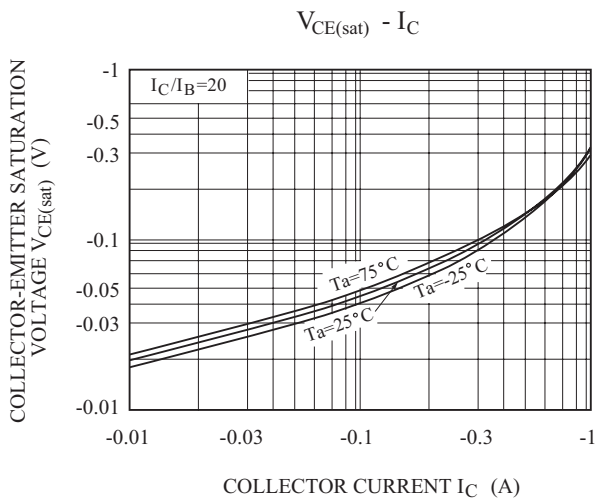
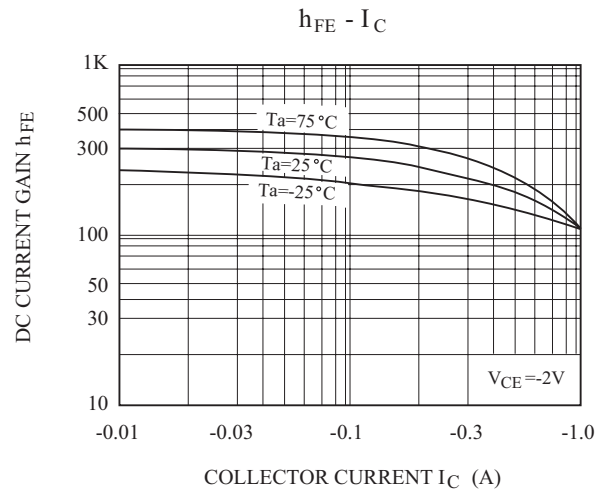
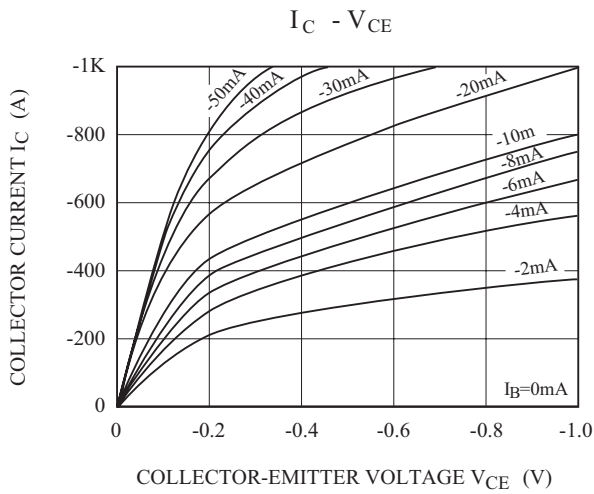
CHARACTERISTIC		SYMBOL	TEST CONDITION	MIN.	TYP.	MAX.	UNIT
Collector Cut-off Current		I_{CBO}	$V_{CB}=-40V, I_E=0$	-	-	-0.1	μA
Emitter Cut-off Current		I_{EBO}	$V_{EB}=-4V, I_C=0$	-	-	-0.1	μA
Collector-Base Breakdown Voltage		$V_{(BR)CBO}$	$I_C=-10\mu A, I_E=0$	-50	-	-	V
Collector-Emitter Breakdown Voltage		$V_{(BR)CES}$	$I_C=-100\mu A, V_{BE}=0$	-50	-	-	V
		$V_{(BR)CEO}$	$I_C=-1mA, I_B=0$	-50	-	-	V
Emitter-Base Breakdown Voltage		$V_{(BR)EBO}$	$I_E=-10\mu A, I_C=0$	-5	-	-	V
Collector-Emitter Saturation Voltage		$V_{CE(sat)1}$	$I_C=-500mA, I_B=-10mA$	-	-280	-430	mV
		$V_{CE(sat)2}$	$I_C=-300mA, I_B=-6mA$	-	-145	-220	mV
Base-Emitter Saturation Voltage		$V_{BE(sat)}$	$I_C=-500mA, I_B=-10mA$	-	-0.81	-1.2	V
DC Current Gain		h_{FE}	$V_{CE}=-2V, I_C=-100mA$	200	-	560	
Transition Frequency		f_T	$V_{CE}=-10V, I_C=-300mA$	-	420	-	MHz
Collector Output Capacitance		C_{ob}	$V_{CB}=-10V, f=1MHz$	-	9	-	pF
Switching Time	Turn-On Time	t_{on}		-	35	-	nS
	Storage Time	t_{stg}		-	170	-	
	Fall Time	t_f		-	30	-	



Marking

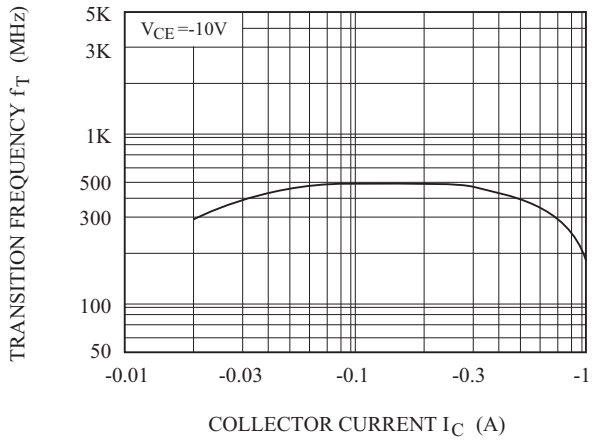


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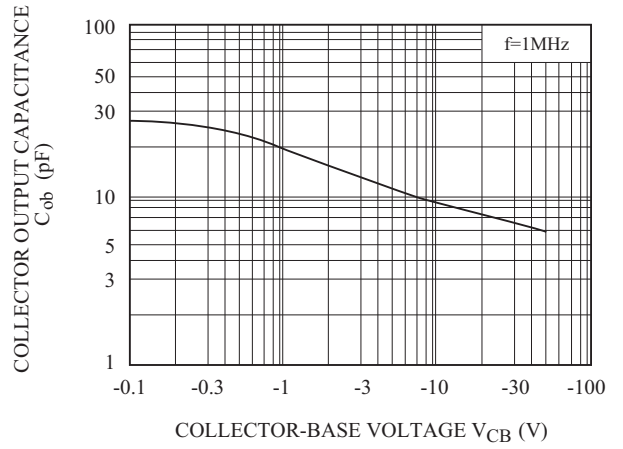


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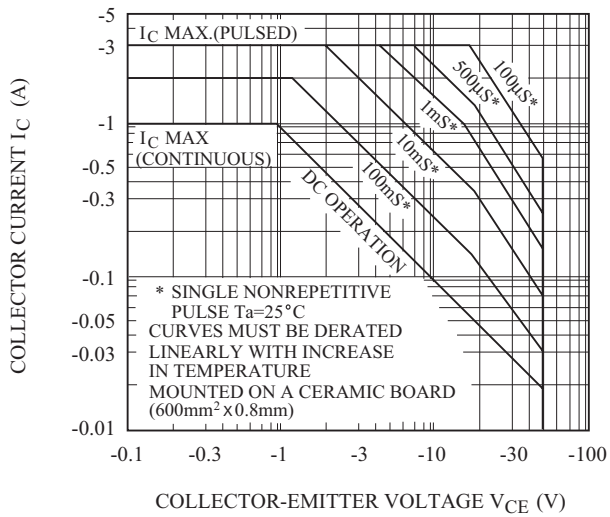
$f_T - I_C$



$C_{ob} - V_{CB}$



SAFE OPERATING AREA



$P_c - T_a$

